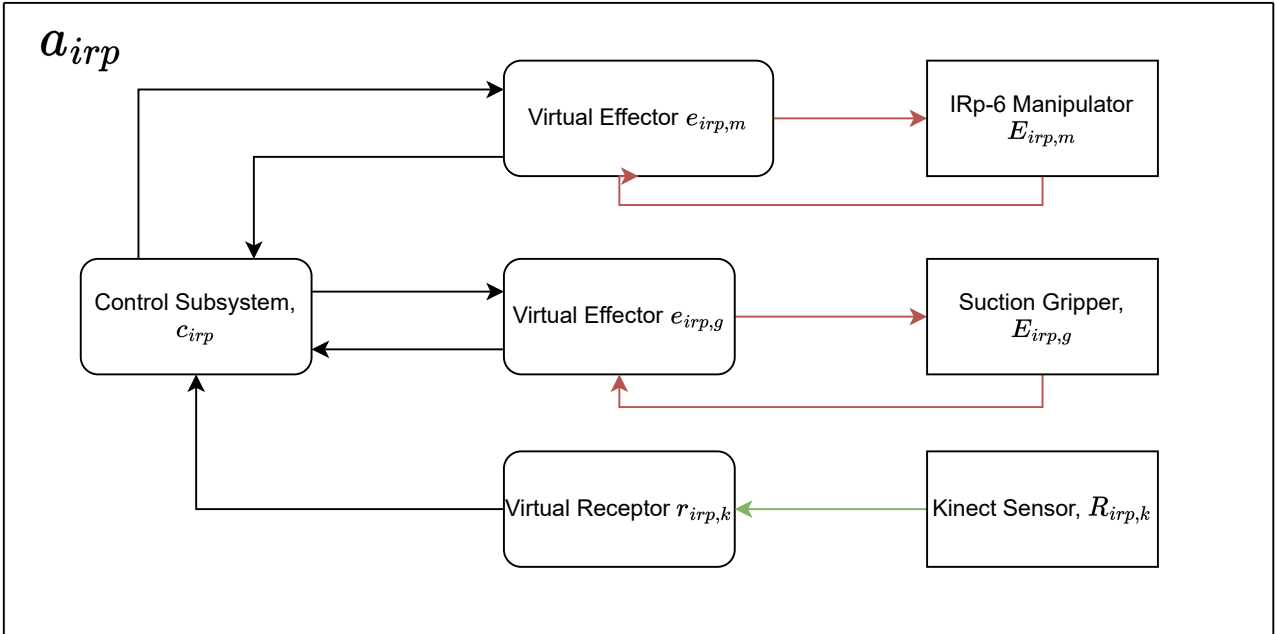
a_{irp}
Virtual Effector $e_{irp,m}$
IRp-6 Manipulator $E_{irp,m}$
Control Subsystem, c_{irp}
Virtual Effector $e_{irp,g}$
Suction Gripper, $E_{irp,g}$
Virtual Receptor $r_{irp,k}$
Kinect Sensor, $R_{irp,k}$